

Non-Parametric Tests for Spatial Dependence



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UNIVERSITÄT
Universität der Bundeswehr Hamburg

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Christian H. Weiß

Department of Mathematics & Statistics
Helmut Schmidt University, Hamburg

Hee-Young Kim

Department of Bigdata Science
Korea University, Sejong, South Korea



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Ordinal Patterns in Time Series

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Introduction

Bandt & Pompe (2002) introduced **ordinal patterns** (OPs) as complexity measures for time series characterized by *“simplicity, extremely fast calculation, robustness, and invariance with respect to nonlinear monotonous transformations”*.

Basic idea in time-series case: map segments

$\mathbf{X}_t = (X_t, X_{t+1}, \dots, X_{t+m-1})$ of length m from

continuously distrib., real-valued process $(X_t)_{t \in \mathbb{Z} = \{\dots, -1, 0, 1, \dots\}}$

onto permutations from symmetric group S_m of order m ,

where selected $\pi_t \in S_m = \{\pi^{[1]}, \dots, \pi^{[m!]} \}$ expresses

order among values in \mathbf{X}_t in certain way: (\dots) .

Rank representation, see Berger et al. (2019):

Entries of $\pi = (r_1, \dots, r_m) \in S_m$ express ranks within $\mathbf{x} = (x_1, \dots, x_m) \in \mathbb{R}^m$, i. e.,

$$r_k < r_l \quad \Leftrightarrow \quad x_k < x_l \quad \text{or} \quad (x_k = x_l \text{ and } k < l)$$

for all $k, l \in \{1, \dots, m\}$. Here, “ $x_k = x_l$ ” if ties within \mathbf{x} .

Example: $(1.2, -0.7, 3.4, 1.9) \mapsto (2, 1, 4, 3),$
 $(1.2, -0.7, 3.4, -0.7) \mapsto (3, 1, 4, 2).$

Marginal distribution of OP series (π_t) provides insights into **serial dependence structure** of original process (X_t) .

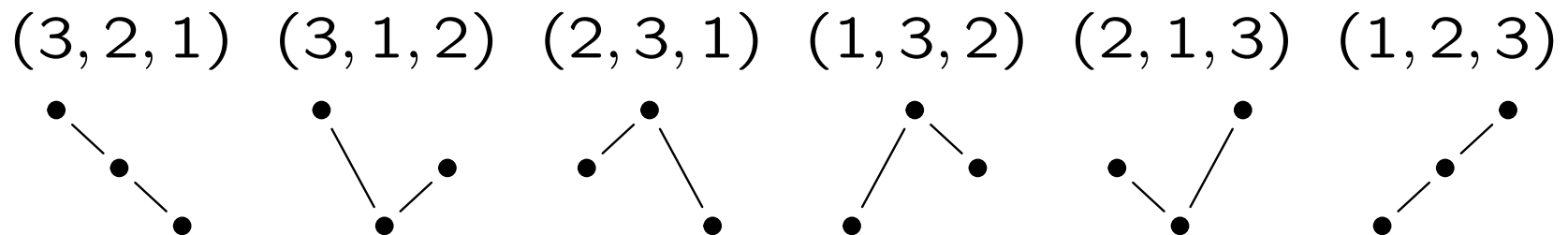
Focus on $m!$ -dimensional **pmf vector** p (or sample pmf \hat{p}),
with k th component being $p_k = P(\pi_t = \pi^{[k]})$.

Here, order m of OPs (thus dimension $m!$) chosen by user.

However, range of π_t quickly increases with m as $|S_m| = m!$,
so estimation \hat{p} of p quickly difficult in practice.

Therefore, in time series analysis,

convenient choice is $m = 3$ (Bandt, 2019):



Let (X_t) be *continuously distributed* real-valued process, independent and identically distributed (i. i. d.) *under null*. Probability of ties = 0, so ties at most rarely in data.

Following **properties** crucial for dependence tests:

1. OPs invariant w.r.t. strictly monotonically increasing transformations of X_t . Thus, OPs do not depend on actual marginal distribution of $(X_t)_{\mathbb{N}}$ (**distribution-free** approach).
2. $(X_t)_{\mathbb{N}}$ is i. i. d. under null (\rightarrow exchangeability).

Thus, π_t discrete uniform on S_m , i. e., $P(\pi_t = \pi) = 1/m!$ for each $\pi \in S_m$ (**no parameter estimation** required).

OP-test statistics built upon \hat{p} ,
closed-form asymptotics in Weiß (2022),
allow for non-parametric testing of i. i. d.-null.

Here: no time series data, but
spatial data in regular two-dimensional grid,
generated by **random field** (being i. i. d. under null).

Outline: *spatial* OPs and (refined) “types”,
possible test statistics and asymptotics,
performance analyses by simulations,
real-data applications.



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Testing for Spatial Dependence in Random Fields

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Asymptotics & Types

Real-valued and continuously distributed **spatial data**

occurring in regular two-dimensional grid: $(X_t)_{t \in \mathbb{Z}^2}$.

(random field, spatial process in plane, regular lattice structure)

Data rectangles $(x_t) = (x_{t_1, t_2})$ with $0 \leq t_1 \leq m$ and $0 \leq t_2 \leq n$.

Infer dependence in (X_t) via **spatial OPs** (SOPs),

due to Ribeiro et al. (2012) and Bandt & Wittfeld (2023).

$m_1 \times m_2$ -SOP computed from $m_1 \times m_2$ -rectangle from (x_t) :

1. concatenate *rows* into vector of length $m_1 \cdot m_2$,
2. compute corresponding $(m_1 \cdot m_2)$ th-order OP from $S_{m_1 \cdot m_2}$,
3. transform back into $m_1 \times m_2$ -matrix in *row-wise* manner.

As $|S_{m_1 \cdot m_2}| = (m_1 \cdot m_2)!$ quickly unfeasibly large,

Bandt & Wittfeld (2023) recommend focus on 2×2 -**SOPs**:

$$\mathbf{x}_t = \begin{pmatrix} X_{t_1-1, t_2-1} & X_{t_1-1, t_2} \\ X_{t_1, t_2-1} & X_{t_1, t_2} \end{pmatrix} =: \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix} \mapsto \begin{pmatrix} r_1 & r_2 \\ r_3 & r_4 \end{pmatrix},$$

where $(r_1, r_2, r_3, r_4) \in S_4$ is OP of (x_1, x_2, x_3, x_4) .

Bandt & Wittfeld (2023): further partition into **types**,

$$\mathcal{S}_1 = \left\{ \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}, \begin{pmatrix} 2 & 1 \\ 4 & 3 \end{pmatrix}, \begin{pmatrix} 2 & 4 \\ 1 & 3 \end{pmatrix}, \begin{pmatrix} 3 & 1 \\ 4 & 2 \end{pmatrix}, \begin{pmatrix} 3 & 4 \\ 1 & 2 \end{pmatrix}, \begin{pmatrix} 4 & 2 \\ 3 & 1 \end{pmatrix}, \begin{pmatrix} 4 & 3 \\ 2 & 1 \end{pmatrix} \right\},$$

$$\mathcal{S}_2 = \left\{ \begin{pmatrix} 1 & 2 \\ 4 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 2 & 1 \\ 3 & 4 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix}, \begin{pmatrix} 3 & 2 \\ 4 & 1 \end{pmatrix}, \begin{pmatrix} 3 & 4 \\ 2 & 1 \end{pmatrix}, \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}, \begin{pmatrix} 4 & 3 \\ 1 & 2 \end{pmatrix} \right\},$$

$$\mathcal{S}_3 = \left\{ \begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 4 \\ 3 & 2 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 4 & 1 \end{pmatrix}, \begin{pmatrix} 2 & 4 \\ 3 & 1 \end{pmatrix}, \begin{pmatrix} 3 & 1 \\ 2 & 4 \end{pmatrix}, \begin{pmatrix} 3 & 2 \\ 1 & 4 \end{pmatrix}, \begin{pmatrix} 4 & 1 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 4 & 2 \\ 1 & 3 \end{pmatrix} \right\}.$$

Visual representation of types

$$\mathcal{S}_1 = \left\{ \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}, \begin{pmatrix} 2 & 1 \\ 4 & 3 \end{pmatrix}, \begin{pmatrix} 2 & 4 \\ 1 & 3 \end{pmatrix}, \begin{pmatrix} 3 & 1 \\ 4 & 2 \end{pmatrix}, \begin{pmatrix} 3 & 4 \\ 1 & 2 \end{pmatrix}, \begin{pmatrix} 4 & 2 \\ 3 & 1 \end{pmatrix}, \begin{pmatrix} 4 & 3 \\ 2 & 1 \end{pmatrix} \right\},$$

$$\mathcal{S}_2 = \left\{ \begin{pmatrix} 1 & 2 \\ 4 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 2 & 1 \\ 3 & 4 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix}, \begin{pmatrix} 3 & 2 \\ 4 & 1 \end{pmatrix}, \begin{pmatrix} 3 & 4 \\ 2 & 1 \end{pmatrix}, \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}, \begin{pmatrix} 4 & 3 \\ 1 & 2 \end{pmatrix} \right\},$$

$$\mathcal{S}_3 = \left\{ \begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 4 \\ 3 & 2 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 4 & 1 \end{pmatrix}, \begin{pmatrix} 2 & 4 \\ 3 & 1 \end{pmatrix}, \begin{pmatrix} 3 & 1 \\ 2 & 4 \end{pmatrix}, \begin{pmatrix} 3 & 2 \\ 1 & 4 \end{pmatrix}, \begin{pmatrix} 4 & 1 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 4 & 2 \\ 1 & 3 \end{pmatrix} \right\}$$

by arrows along increasing rank:

$$\mathcal{S}_1 = \left\{ \begin{array}{c} \blacktriangleright \\ \blacktriangleleft \\ \blacktriangleleft \\ \blacktriangleright \\ \blacktriangleleft \\ \blacktriangleright \\ \blacktriangleleft \\ \blacktriangleright \end{array} \right\}, \quad (\text{"Z-type"})$$

$$\mathcal{S}_2 = \left\{ \begin{array}{c} \blacktriangleleft \\ \blacktriangleup \\ \blacktriangleright \\ \blacktriangleleft \\ \blacktriangleup \\ \blacktriangleright \\ \blacktriangleup \\ \blacktriangleleft \end{array} \right\}, \quad (\text{"U-type"})$$

$$\mathcal{S}_3 = \left\{ \begin{array}{c} \blacktriangleleft \\ \blacktriangleup \\ \blacktriangleleft \\ \blacktriangleup \\ \blacktriangleleft \\ \blacktriangleup \\ \blacktriangleleft \\ \blacktriangleup \end{array} \right\}. \quad (\text{"X-type"})$$

3 types more feasible in small data than 24 SOPs.

Type 1: monotonic behaviour both along rows and columns.

Type 2: uniquely increase/decrease only along one direction.

Type 3: lowest and highest ranks on either main or antidiagonal.

type = rank number which shares diagonal with rank 4.

Example: arthropods data from R-package agridat:

$$\begin{array}{cccc}
 35 & 24 & 18 & \cdots t_2 \\
 18 & 32 & 14 & \cdots \\
 \boxed{17} & \boxed{21} & 40 & \cdots \\
 \boxed{17} & \boxed{34} & 25 & \cdots \\
 \vdots & \vdots & \vdots & \cdots \\
 t_1 & & &
 \end{array}
 \rightarrow
 \begin{array}{ccc}
 \begin{pmatrix} 4 & 2 \\ 1 & 3 \end{pmatrix} & \begin{pmatrix} 3 & 2 \\ 4 & 1 \end{pmatrix} & \cdots t_2 \\
 \begin{pmatrix} 2 & 4 \\ 1 & 3 \end{pmatrix} & \begin{pmatrix} 3 & 1 \\ 2 & 4 \end{pmatrix} & \cdots \\
 \boxed{\begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}} & \begin{pmatrix} 1 & 4 \\ 3 & 2 \end{pmatrix} & \cdots \\
 \vdots & \vdots & \cdots \\
 t_1 & &
 \end{array}
 \rightarrow
 \begin{array}{ccc}
 3 & 2 & \cdots t_2 \\
 1 & 3 & \cdots \\
 \boxed{1} & 3 & \cdots \\
 \vdots & \vdots & \cdots \\
 t_1 & &
 \end{array}$$

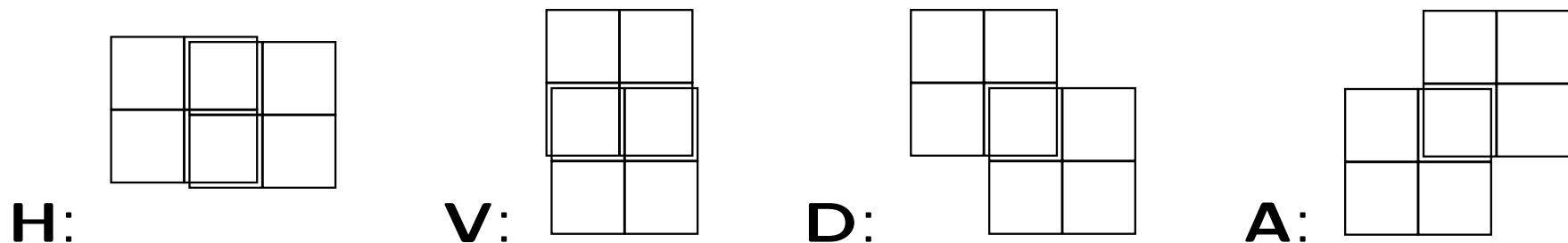
$\mathbf{p}, \hat{\mathbf{p}}$ use **lexicographic ordering** of SOPs; $\mathbf{p}_0 = (\frac{1}{24}, \dots, \frac{1}{24})^\top$.

Theorem: (Weiß & Kim, 2024a)

Under i. i. d.-null, $\sqrt{mn} (\hat{\mathbf{p}} - \mathbf{p}_0) \xrightarrow{d} N(\mathbf{0}, \Sigma_{\text{full}})$

$$\Sigma_{\text{full}} = \text{diag}(\mathbf{p}_0) - \mathbf{p}_0 \mathbf{p}_0^\top + \left(\mathbf{D} + \mathbf{D}^\top + \mathbf{A} + \mathbf{A}^\top - 4 \mathbf{p}_0 \mathbf{p}_0^\top \right) + \left(\mathbf{H} + \mathbf{H}^\top - 2 \mathbf{p}_0 \mathbf{p}_0^\top \right) + \left(\mathbf{V} + \mathbf{V}^\top - 2 \mathbf{p}_0 \mathbf{p}_0^\top \right).$$

Considers different overlaps of 2×2 -SOPs:



Closed-form expression for Σ_{full} from Weiß & Kim (2024a).

Entries of matrix $20160 \cdot \Sigma_{\text{full}}$:

	π_1	π_2	π_3	π_4	π_5	π_6	π_7	π_8	π_9	π_{10}	π_{11}	π_{12}	π_{13}	π_{14}	π_{15}	π_{16}	π_{17}	π_{18}	π_{19}	π_{20}	π_{21}	π_{22}	π_{23}	π_{24}
π_1	773	-75	-99	-95	-67	-111	-75	-27	-67	41	-35	-3	-95	-35	-111	-59	181	61	41	-59	-3	-83	61	-59
π_2	-75	645	-67	-175	13	-87	101	-75	-139	-87	-59	29	13	-67	-11	13	61	-59	-11	-139	-7	-59	181	61
π_3	-99	-67	773	-111	-75	-95	-67	-35	-75	-3	-27	41	-111	181	-95	61	-35	-59	-3	61	41	-59	-59	-83
π_4	-95	-175	-111	685	-87	-107	13	-95	-11	-107	41	-59	157	-111	37	-87	-3	29	37	-11	29	41	-7	-3
π_5	-67	13	-75	-87	645	-175	-139	-59	101	29	-75	-87	-11	61	13	-59	-67	13	-7	181	-11	61	-139	-59
π_6	-111	-87	-95	-107	-175	685	-11	41	13	-59	-95	-107	37	-3	157	29	-111	-87	29	-7	37	-3	-11	41
π_7	-75	101	-67	13	-139	-11	645	-75	13	-11	-59	-7	-175	-67	-87	-139	61	181	-87	13	29	-59	-59	61
π_8	-27	-75	-35	-95	-59	41	-75	773	-59	-111	-83	-3	-95	-99	41	-67	-59	61	-111	-67	-3	-35	61	181
π_9	-67	-139	-75	-11	101	13	13	-59	645	-7	-75	-11	-87	61	-175	181	-67	-139	29	-59	-87	61	13	-59
π_{10}	41	-87	-3	-107	29	-59	-11	-111	-7	685	-3	-107	37	-95	29	-175	41	-87	157	13	37	-95	-11	-111
π_{11}	-35	-59	-27	41	-75	-95	-59	-83	-75	-3	773	-111	41	-59	-95	61	-99	-67	-3	61	-111	181	-67	-35
π_{12}	-3	29	41	-59	-87	-107	-7	-3	-11	-107	-111	685	29	41	37	-87	-95	-175	37	-11	157	-111	13	-95
π_{13}	-95	13	-111	157	-11	37	-175	-95	-87	37	41	29	685	-111	-107	-11	-3	-7	-107	-87	-59	41	29	-3
π_{14}	-35	-67	181	-111	61	-3	-67	-99	61	-95	-59	41	-111	773	-3	-75	-83	-59	-95	-75	41	-27	-59	-35
π_{15}	-111	-11	-95	37	13	157	-87	41	-175	29	-95	37	-107	-3	685	-7	-111	-11	-59	29	-107	-3	-87	41
π_{16}	-59	13	61	-87	-59	29	-139	-67	181	-175	61	-87	-11	-75	-7	645	-59	13	13	101	-11	-75	-139	-67
π_{17}	181	61	-35	-3	-67	-111	61	-59	-67	41	-99	-95	-3	-83	-111	-59	773	-75	41	-59	-95	-35	-75	-27
π_{18}	61	-59	-59	29	13	-87	181	61	-139	-87	-67	-175	-7	-59	-11	13	-75	645	-11	-139	13	-67	101	-75
π_{19}	41	-11	-3	37	-7	29	-87	-111	29	157	-3	37	-107	-95	-59	13	41	-11	685	-175	-107	-95	-87	-111
π_{20}	-59	-139	61	-11	181	-7	13	-67	-59	13	61	-11	-87	-75	29	101	-59	-139	-175	645	-87	-75	13	-67
π_{21}	-3	-7	41	29	-11	37	29	-3	-87	37	-111	157	-59	41	-107	-11	-95	13	-107	-87	685	-111	-175	-95
π_{22}	-83	-59	-59	41	61	-3	-59	-35	61	-95	181	-111	41	-27	-3	-75	-35	-67	-95	-75	-111	773	-67	-99
π_{23}	61	181	-59	-7	-139	-11	-59	61	13	-11	-67	13	29	-59	-87	-139	-75	101	-87	13	-175	-67	645	-75
π_{24}	-59	61	-83	-3	-59	41	61	181	-59	-111	-35	-95	-3	-35	41	-67	-27	-75	-111	-67	-95	-99	-75	773

By above Theorem, derive asymptotics of any aggregation.

Concerning **types**, define transformation matrix

$\mathbf{T}_{\text{types}} \in \{0, 1\}^{3 \times 24}$ as 1 iff j^{th} SOP of type i ,
and 0 otherwise.

Corollary: (Bandt & Wittfeld, 2023)

Under i. i. d.-null, asymptotic covariance of type frequencies

$$\Sigma_{\text{types}} = \mathbf{T}_{\text{types}} \Sigma_{\text{full}} \mathbf{T}_{\text{types}}^{\top} = \frac{1}{45} \begin{pmatrix} 11 & -5 & -6 \\ -5 & 11 & -6 \\ -6 & -6 & 12 \end{pmatrix},$$

with non-zero eigenvalues $\frac{2}{5}$ and $\frac{16}{45}$.

Bandt & Wittfeld (2023) proposed following type statistics:

$$\hat{\tau} = \hat{p}_1 - 1/3 \quad \text{and} \quad \hat{\kappa} = \hat{p}_2 - \hat{p}_3,$$

$$\tilde{\tau} = \hat{p}_3 - 1/3 \quad \text{and} \quad \tilde{\kappa} = \hat{p}_1 - \hat{p}_2.$$

Corollary: Under i. i. d.-null,

$\sqrt{mn} (\hat{\tau}, \hat{\kappa}) \xrightarrow{d} N(\mathbf{0}, \Sigma')$ and $\sqrt{mn} (\tilde{\tau}, \tilde{\kappa}) \xrightarrow{d} N(\mathbf{0}, \Sigma'')$, where

$$\Sigma' = \frac{1}{45} \begin{pmatrix} 11 & 1 \\ 1 & 35 \end{pmatrix}, \quad \Sigma'' = \frac{4}{45} \begin{pmatrix} 3 & 0 \\ 0 & 8 \end{pmatrix}.$$

⇒ four **non-parametric tests for spatial dependence:**

$\hat{\tau}$ -test, $\hat{\kappa}$ -test, $\tilde{\tau}$ -test, $\tilde{\kappa}$ -test.

Performance analyses in Weiß & Kim (2024a):

While spatial ACF superior for *linear unilateral* DGPs, SOP-based tests often superior in presence of *outliers*, for *non-linear* DGPs, and for *bilateral* spatial DGPs.

$\tilde{\tau}$ -test outperforms all other type-tests!

However, types imply a three-part partition $\mathcal{S}_1 \cup \mathcal{S}_2 \cup \mathcal{S}_3$.

Reducing real-valued spatial data set to three types only, may lose information for uncovering spatial dependence.

⇒ Develop “**refined types**” to preserve more information!



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Testing for Spatial Dependence in Random Fields

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Refined Types & Entropy

1st refinement $\mathcal{S}_i = \mathcal{S}_{i.1} \cup \mathcal{S}_{i.2}$ in Weiß & Kim (2024b):

rotation types (invariant w.r.t. rotation)

$$\mathcal{S}_{1.1} = \{\pi_1, \pi_{11}, \pi_{14}, \pi_{24}\} = \left\{ \begin{array}{c} \blacktriangleright \\ \blacktriangleup \\ \blacktriangledown \\ \blacktriangleleft \end{array} \right\},$$

$$\mathcal{S}_{1.2} = \{\pi_3, \pi_8, \pi_{17}, \pi_{22}\} = \left\{ \begin{array}{c} \blacktriangledown \\ \blacktriangleleft \\ \blacktriangleright \\ \blacktriangleup \end{array} \right\},$$

$$\mathcal{S}_{2.1} = \{\pi_2, \pi_9, \pi_{18}, \pi_{20}\} = \left\{ \begin{array}{c} \blacktriangleleft \\ \blacktriangledown \\ \blacktriangleright \\ \blacktriangleup \end{array} \right\},$$

$$\mathcal{S}_{2.2} = \{\pi_5, \pi_7, \pi_{16}, \pi_{23}\} = \left\{ \begin{array}{c} \blacktriangleup \\ \blacktriangleright \\ \blacktriangledown \\ \blacktriangleleft \end{array} \right\},$$

$$\mathcal{S}_{3.1} = \{\pi_4, \pi_{12}, \pi_{15}, \pi_{19}\} = \left\{ \begin{array}{c} \blacktriangledown \\ \blacktriangleup \\ \blacktriangledown \\ \blacktriangleup \end{array} \right\},$$

$$\mathcal{S}_{3.2} = \{\pi_6, \pi_{10}, \pi_{13}, \pi_{21}\} = \left\{ \begin{array}{c} \blacktriangleup \\ \blacktriangledown \\ \blacktriangledown \\ \blacktriangleup \end{array} \right\}.$$

1st refinement $\mathcal{S}_i = \mathcal{S}_{i.1} \cup \mathcal{S}_{i.2}$ in Weiß & Kim (2024b):
rotation types.

Corollary: Under i. i. d.-null,

asymptotic covariance of rotation-type frequencies

$$\Sigma_{\text{rot}} = \mathbf{T}_{\text{rot}} \Sigma_{\text{full}} \mathbf{T}_{\text{rot}}^{\top} = \frac{1}{180} \begin{pmatrix} 23 & -1 & -5 & -5 & -6 & -6 \\ -1 & 23 & -5 & -5 & -6 & -6 \\ -5 & -5 & 11 & 11 & -6 & -6 \\ -5 & -5 & 11 & 11 & -6 & -6 \\ -6 & -6 & -6 & -6 & 25 & -1 \\ -6 & -6 & -6 & -6 & -1 & 25 \end{pmatrix},$$

with non-zero eigenvalues $\frac{1}{5}$, $\frac{8}{45}$, $\frac{13}{90}$, and $\frac{2}{15}$.

2nd refinement $\mathcal{S}_i = \mathcal{S}_{i.1} \cup \mathcal{S}_{i.2}$ in Weiß & Kim (2024b):

direction types (w.r.t. positions of maximal ranks)

$$\mathcal{S}_{1.1} = \{\pi_1, \pi_8, \pi_{17}, \pi_{24}\} = \left\{ \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, \begin{pmatrix} 2 & 1 \\ 4 & 3 \end{pmatrix}, \begin{pmatrix} 3 & 4 \\ 1 & 2 \end{pmatrix}, \begin{pmatrix} 4 & 3 \\ 2 & 1 \end{pmatrix} \right\},$$

$$\mathcal{S}_{1.2} = \{\pi_3, \pi_{11}, \pi_{14}, \pi_{22}\} = \left\{ \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}, \begin{pmatrix} 2 & 4 \\ 1 & 3 \end{pmatrix}, \begin{pmatrix} 3 & 1 \\ 4 & 2 \end{pmatrix}, \begin{pmatrix} 4 & 2 \\ 3 & 1 \end{pmatrix} \right\},$$

$$\mathcal{S}_{2.1} = \{\pi_2, \pi_7, \pi_{18}, \pi_{23}\} = \left\{ \begin{pmatrix} 1 & 2 \\ 4 & 3 \end{pmatrix}, \begin{pmatrix} 2 & 1 \\ 3 & 4 \end{pmatrix}, \begin{pmatrix} 3 & 4 \\ 2 & 1 \end{pmatrix}, \begin{pmatrix} 4 & 3 \\ 1 & 2 \end{pmatrix} \right\},$$

$$\mathcal{S}_{2.2} = \{\pi_5, \pi_9, \pi_{16}, \pi_{20}\} = \left\{ \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix}, \begin{pmatrix} 3 & 2 \\ 4 & 1 \end{pmatrix}, \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \right\},$$

$$\mathcal{S}_{3.1} = \{\pi_4, \pi_6, \pi_{10}, \pi_{12}\} = \left\{ \begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 4 \\ 3 & 2 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 4 & 1 \end{pmatrix}, \begin{pmatrix} 2 & 4 \\ 3 & 1 \end{pmatrix} \right\},$$

$$\mathcal{S}_{3.2} = \{\pi_{13}, \pi_{15}, \pi_{19}, \pi_{21}\} = \left\{ \begin{pmatrix} 3 & 1 \\ 2 & 4 \end{pmatrix}, \begin{pmatrix} 3 & 2 \\ 1 & 4 \end{pmatrix}, \begin{pmatrix} 4 & 1 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 4 & 2 \\ 1 & 3 \end{pmatrix} \right\}.$$

2nd refinement $\mathcal{S}_i = \mathcal{S}_{i.1} \cup \mathcal{S}_{i.2}$ in Weiß & Kim (2024b):
direction types.

Corollary: Under i. i. d.-null,

asymptotic covariance of direction-type frequencies

$$\Sigma_{\text{dir}} = \mathbf{T}_{\text{dir}} \Sigma_{\text{full}} \mathbf{T}_{\text{dir}}^{\top} = \frac{1}{1260} \begin{pmatrix} 217 & -63 & -7 & -63 & -42 & -42 \\ -63 & 217 & -63 & -7 & -42 & -42 \\ -7 & -63 & 217 & -63 & -42 & -42 \\ -63 & -7 & -63 & 217 & -42 & -42 \\ -42 & -42 & -42 & -42 & 103 & 65 \\ -42 & -42 & -42 & -42 & 65 & 103 \end{pmatrix},$$

with non-zero eigenvalues $\frac{4}{15}$, $\frac{1}{5}$, $\frac{8}{45}$ (twice), and $\frac{19}{630}$.

3rd refinement $\mathcal{S}_i = \mathcal{S}_{i.1} \cup \mathcal{S}_{i.2}$ in Weiß & Kim (2024b):

diagonal types (w.r.t. diagonal with rank 4)

$$\mathcal{S}_{1.1} = \left\{ \pi_1, \pi_3, \pi_{22}, \pi_{24} \right\} = \left\{ \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}, \begin{pmatrix} 4 & 2 \\ 3 & 1 \end{pmatrix}, \begin{pmatrix} 4 & 3 \\ 2 & 1 \end{pmatrix} \right\},$$

$$\mathcal{S}_{1.2} = \left\{ \pi_8, \pi_{11}, \pi_{14}, \pi_{17} \right\} = \left\{ \begin{pmatrix} 2 & 1 \\ 4 & 3 \end{pmatrix}, \begin{pmatrix} 2 & 4 \\ 1 & 3 \end{pmatrix}, \begin{pmatrix} 3 & 1 \\ 4 & 2 \end{pmatrix}, \begin{pmatrix} 3 & 4 \\ 1 & 2 \end{pmatrix} \right\},$$

$$\mathcal{S}_{2.1} = \left\{ \pi_7, \pi_9, \pi_{20}, \pi_{23} \right\} = \left\{ \begin{pmatrix} 2 & 1 \\ 3 & 4 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix}, \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}, \begin{pmatrix} 4 & 3 \\ 1 & 2 \end{pmatrix} \right\},$$

$$\mathcal{S}_{2.2} = \left\{ \pi_2, \pi_5, \pi_{16}, \pi_{18} \right\} = \left\{ \begin{pmatrix} 1 & 2 \\ 4 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 3 & 2 \\ 4 & 1 \end{pmatrix}, \begin{pmatrix} 3 & 4 \\ 2 & 1 \end{pmatrix} \right\},$$

$$\mathcal{S}_{3.1} = \left\{ \pi_{13}, \pi_{15}, \pi_{19}, \pi_{21} \right\} = \left\{ \begin{pmatrix} 3 & 1 \\ 2 & 4 \end{pmatrix}, \begin{pmatrix} 3 & 2 \\ 1 & 4 \end{pmatrix}, \begin{pmatrix} 4 & 1 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 4 & 2 \\ 1 & 3 \end{pmatrix} \right\},$$

$$\mathcal{S}_{3.2} = \left\{ \pi_4, \pi_6, \pi_{10}, \pi_{12} \right\} = \left\{ \begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 4 \\ 3 & 2 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 4 & 1 \end{pmatrix}, \begin{pmatrix} 2 & 4 \\ 3 & 1 \end{pmatrix} \right\},$$

3rd refinement $\mathcal{S}_i = \mathcal{S}_{i.1} \cup \mathcal{S}_{i.2}$ in Weiß & Kim (2024b):
diagonal types.

Corollary: Under i. i. d.-null,

asymptotic covariance of diagonal-type frequencies

$$\Sigma_{\text{diag}} = \dots = \frac{1}{1260} \begin{pmatrix} 133 & 21 & -35 & -35 & -42 & -42 \\ 21 & 133 & -35 & -35 & -42 & -42 \\ -35 & -35 & 153 & 1 & -80 & -4 \\ -35 & -35 & 1 & 153 & -4 & -80 \\ -42 & -42 & -80 & -4 & 103 & 65 \\ -42 & -42 & -4 & -80 & 65 & 103 \end{pmatrix},$$

with non-zero eigenvalues $\frac{1}{5}$, $\frac{8}{45}$, $\frac{19}{126}$, and $\frac{4}{45}$.

Test statistics: Like in Bandt (2019); Weiß (2022), we use entropy, extropy, and distance to white noise,

$$\widehat{H} := H(\widehat{\mathbf{p}}) = -\sum_{k=1}^q \widehat{p}_k \ln \widehat{p}_k,$$

$$\widehat{H}_{\text{ex}} := H_{\text{ex}}(\widehat{\mathbf{p}}) = -\sum_{k=1}^q (1 - \widehat{p}_k) \ln(1 - \widehat{p}_k),$$

$$\widehat{\Delta} := \Delta(\widehat{\mathbf{p}}) = \sum_{k=1}^q (\widehat{p}_k - 1/q)^2.$$

Adapting **Theorem 2.1** in Weiß (2022),

$$mn \widehat{\Delta}, \quad -mn \frac{2}{q} \left(\widehat{H} - \ln q \right), \quad -2mn \left(1 - \frac{1}{q} \right) \left(\widehat{H}_{\text{ex}} - (q-1) \ln \left(\frac{q}{q-1} \right) \right)$$

asymptotically distributed like $\sum_{i=1}^l \lambda_i \cdot \chi_{r_i}^2$,

where $\lambda_1, \dots, \lambda_l$ non-zero eigenvalues of Σ .

Corollary in Weiß & Kim (2024b): For **ordinary types**,

$$mn \widehat{\Delta}, \quad -\frac{2}{3} mn \left(\widehat{H} - \ln 3 \right), \quad -\frac{4}{3} mn \left(\widehat{H}_{\text{ex}} - 2 \ln \left(\frac{3}{2} \right) \right)$$

asymptotically distributed like $\frac{2}{5} \chi_1^2 + \frac{16}{45} \chi_1^2$.

For **refined types**, asymptotic distribution of

$$mn \widehat{\Delta}, \quad -\frac{1}{3} mn \left(\widehat{H} - \ln 6 \right), \quad -\frac{10}{6} mn \left(\widehat{H}_{\text{ex}} - 5 \ln \left(\frac{6}{5} \right) \right)$$

is

$\frac{1}{5} \chi_1^2 + \frac{8}{45} \chi_1^2 + \frac{13}{90} \chi_1^2 + \frac{2}{15} \chi_1^2$	if rotation types,
$\frac{4}{15} \chi_1^2 + \frac{1}{5} \chi_1^2 + \frac{8}{45} \chi_2^2 + \frac{19}{630} \chi_1^2$	if direction types,
$\frac{1}{5} \chi_1^2 + \frac{8}{45} \chi_1^2 + \frac{19}{126} \chi_1^2 + \frac{4}{45} \chi_1^2$	if diagonal types.

Critical values for non-parametric entropy-like tests
via R package `CompQuadForm`.

Important $(1 - \alpha)$ -quantiles of quadratic-form distributions:

α	Ordinary	Rotation	Direction	Diagonal
0.10	1.740201	1.279915	1.637740	1.216170
0.05	2.265401	1.566739	1.999264	1.497222
0.01	3.487299	2.210104	2.813519	2.133017



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UNIVERSITÄT
Universität der Bundeswehr Hamburg

**MATH
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Testing for Spatial Dependence in Random Fields

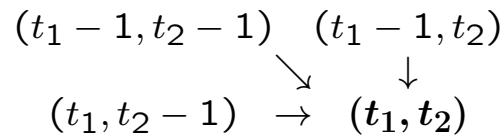
■

 ■
Empirical Investigations

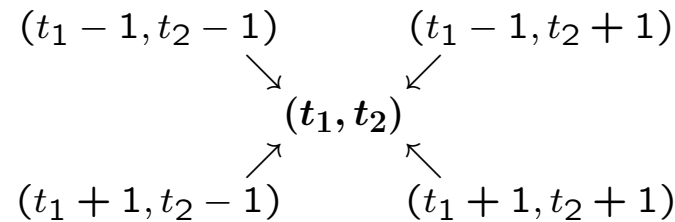
Performance analyses by simulations in Weiß & Kim (2024b).

For power analyses, various unilateral and bilateral spatial DGPs:

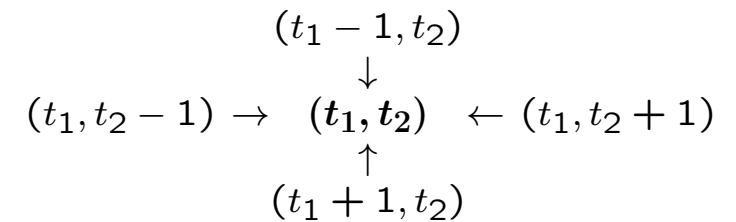
Unilateral:



Bishop:



Rook:



Brief summary:

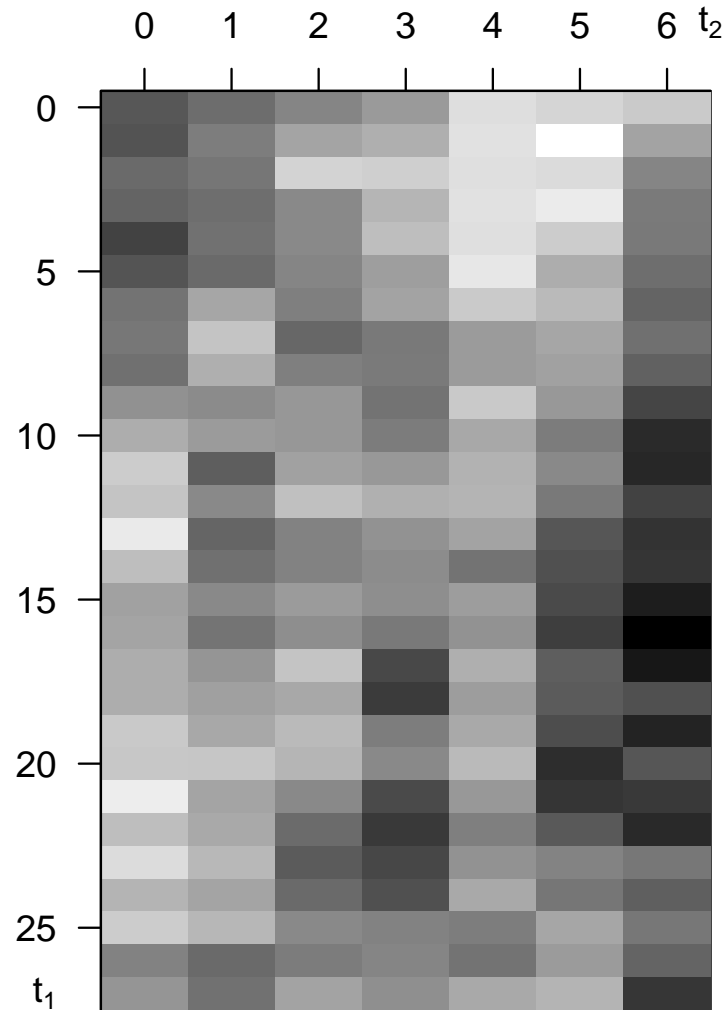
- Size: all tests hold nominal level sufficiently well.
- $\tilde{\tau}$ -test excellent choice for uncovering spatial dependence, but in many cases, further improvements by appropriate form of refined type. (. . .)

Brief summary:

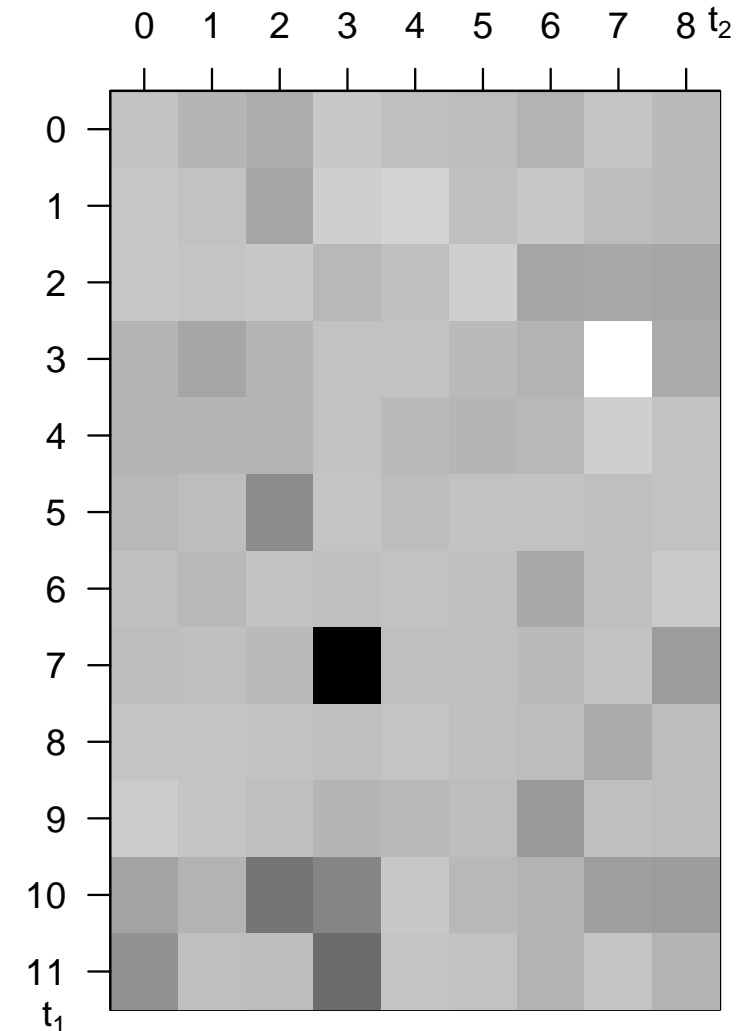
- For unilateral DGPs, diagonal types superior in most cases.
- For bilateral DGPs, $\tilde{\tau}$ -test often superior.
- For bil. DGPs with Rook structure, direction types superior.
- If refined types superior, then extropy most powerful.

Weiß & Kim (2024b): two **real-world data examples**,
yield of barley (in kg) in 28×7 -grid ($m = 27, n = 6$) from
uniformity trial experiment (Kempton & Howes, 1981);
population change in Turku region between 2005 and 2022
in $1 \text{ km} \times 1 \text{ km}$ grid ($m = 11, n = 8$), see Statistics Finland.

Yield of barley:



Population change:



Yield of barley: all tests reject i. i. d.-null (P-values $\approx 10^{-9}$).

Particularly large extropy value for direction types,

mainly $\mathcal{S}_{1.2}$ (32.1%) and $\mathcal{S}_{2.2}$ (36.4%) \Rightarrow “dominant columns”.

$$\mathcal{S}_{1.2} = \left\{ \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}, \begin{pmatrix} 2 & 4 \\ 1 & 3 \end{pmatrix}, \begin{pmatrix} 3 & 1 \\ 4 & 2 \end{pmatrix}, \begin{pmatrix} 4 & 2 \\ 3 & 1 \end{pmatrix} \right\}, \quad \mathcal{S}_{2.2} = \left\{ \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix}, \begin{pmatrix} 3 & 2 \\ 4 & 1 \end{pmatrix}, \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \right\}.$$

Kempton & Howes (1981): “sowing, harvesting and all intermediate farming practices were carried out column by column”.

Population change: extremely large value at $t = (7, 3)$,

but SOPs robust against outliers (by contrast to spatial ACF).

Only diagonal types reject (extropy’s P-value 0.008), mainly

$\mathcal{S}_{1.2}$ (21.6%) and $\mathcal{S}_{2.2}$ (27.3%) \Rightarrow “dominant antidiagonal”.

$$\mathcal{S}_{1.2} = \left\{ \begin{pmatrix} 2 & 1 \\ 4 & 3 \end{pmatrix}, \begin{pmatrix} 2 & 4 \\ 1 & 3 \end{pmatrix}, \begin{pmatrix} 3 & 1 \\ 4 & 2 \end{pmatrix}, \begin{pmatrix} 3 & 4 \\ 1 & 2 \end{pmatrix} \right\}, \quad \mathcal{S}_{2.2} = \left\{ \begin{pmatrix} 1 & 2 \\ 4 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 3 & 2 \\ 4 & 1 \end{pmatrix}, \begin{pmatrix} 3 & 4 \\ 2 & 1 \end{pmatrix} \right\}.$$

SOPs and (refined) types well-interpretable and robust.

If data continuously distributed, then non-parametric tests.

Easily implemented in practice due to closed-form asymptotics.

Direction and diagonal types advantageous for unilateral and certain bilateral DGPs, where entropy statistic most powerful.

Work in progress & future research:

- Control charts based on SOPs and (refined) types, in analogy to Weiß & Testik (2023);
- SOPs based on “generalized OPs” where ties explicitly accounted for, in analogy to Weiß & Schnurr (2024).

Thank You for Your Interest!



HELMUT SCHMIDT
UNIVERSITÄT

Universität der Bundeswehr Hamburg

**MATH
STAT**

Christian H. Weiß

Department of Mathematics & Statistics

Helmut Schmidt University, Hamburg

weissc@hsu-hh.de

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